## De-Integrating Integrated Circuit Preamps

**Less Delivers More?** 

Les Tyler, President, THAT Corporation

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# **Today's Topics**

- Where we've been, and where we're going
  - The old to the "new" topology
- Optimizing this new topology
  - Noise
  - Bandwidth
  - Gain control, taper, & dc offset
  - Output configuration
- Wrap-up

# Out with the Old ... In with the New

Some historical perspective...



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# In the Beginning (for IC Preamps)

- Solid State Music
  - Ron Dow
  - Dan Parks
- SSM 2011 (~1982) – Integrated preamp
  - External feedback
- SSM2015 (~1983)
  - Integrated preamp
  - One external resistor controls gain: R<sub>G</sub>



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# **"Standard" IC Preamp Configuration**

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- Differential input
- Single-ended output
- Current feedback
- Single resistor controls gain – R<sub>G</sub>

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### • Minimum gain: OdB – Requires infinite R<sub>G</sub>



## **Many Followed In SSM's Footsteps**

- SSM2016 (1986)
  - Derek Bowers' design
- SSM2017 (1989)
  - By this time, SSM was part of Analog Devices
- SSM2019 (2003)
   Derek Bowers (at ADI)
- TI INA163 (~2000) - INA217 (2002)
  - INAZI7 (2002)
- THAT 1510 (2004)
- THAT1512 (2004)
  - External R<sub>G</sub>
  - Diff-amp gain: -6dB
  - Credit: Cal Perkins (at Mackie)

### Not considered: AD524 (1982)

- Also included internal R<sub>A</sub> & R<sub>B</sub>, as well as choice of (internal) R<sub>G</sub>
- Scott Wurcer's design
- Noise too high for a mic preamp (~5nV/√Hz)



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### **Benefits of "Standard" Topology**

- Wide bandwidth at high gain due to current, not voltage feedback
- Can be very quiet at high gains

   Many reach 1nV/√Hz voltage noise
- Easy to control gain with single R<sub>G</sub>
- Integrated approach allows wide input dynamic range
  - See G. Hebert's presentation at the 2010 US AES convention

# Detriments of "Standard" Topology

- Feedback network adds noise at low gains
  - Resistor self-noise
  - Current noise in R<sub>G</sub> pins drawn across the feedback network's impedance
- Maximum gain is affected by pot's effective end-resistance
- Smooth taper is hard to achieve – Depends on R<sub>G</sub> vs. R<sub>A</sub> & R<sub>B</sub>
- Must convert output from single-ended to differential to drive A/D converters

### Let's De-Integrate the Topology

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• Start with the "standard" IC



 Remove the output diff amp



## Let's De-Integrate the Topology

 Remove internal R<sub>A</sub> & R<sub>B</sub>



 Take away the external R<sub>G</sub>



## What Does That Leave?

- Uncommitted
  - Completely configurable
- Differential In

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- Differential Out

   OdB common-mode gain
- Current Feedback
- Low Voltage Noise
- THAT's the 1570 & 1583



### The 1570/1583 "Uncommitted" Topology Makes Optimization Easy

- Noise vs. gain
- Bandwidth vs. gain
- Pot end resistance
- Gain vs. pot rotation
- Output amp performance
  - Noise
  - CMRR

# **Optimization Details**

### Noise

Bandwidth Gain control, taper & DC offset Output & Common-Mode Rejection



## Noise Model for 1570/1583-Type Preamp

- Voltage (e<sub>n</sub>) & Current (i<sub>n</sub>) noise flows in each input pin
- e<sub>n</sub> is amplified by gain
   0dB at minimum gain
   +60dB at 60dB gain
- i<sub>n</sub> creates a noise voltage based on the impedance it flows through
  - Then amplified by gain
- Sources are uncorrelated

   Add in RMS fashion (root of the sum of the squares)



## Noise Model for 1570/1583-Type Preamp

- e<sub>nRG</sub> can be lumped into the e<sub>nIN+</sub> and e<sub>nIN-</sub> sources
- Contributions of i<sub>nIN+</sub> & i<sub>nIN-</sub> depend on source impedance at In+ & In-= (R<sub>3</sub>+R<sub>4</sub>+R<sub>5</sub>)||(R<sub>1</sub>+R<sub>2</sub>)
- Contribution of i<sub>nRG</sub> depends on feedback network impedance
  - $= (R_A + R_B) || R_G$
  - Current times impedance generates the voltage
- Because gain varies with R<sub>A</sub>, R<sub>B</sub> & R<sub>G</sub>, relative contribution of each source depends on gain



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### 1570/1583 Noise At High Gains (60dB shown)

- R<sub>G</sub> is small, so i<sub>nR<sub>G</sub></sub> contribution is small
- R<sub>s</sub> is small, so the i<sub>nIN+</sub> & i<sub>nIN-</sub> contributions are small
  - But, if R<sub>s</sub> is large (e.g., open inputs), i<sub>nIN</sub> contributions can be significant
- e<sub>nIN+</sub> & e<sub>nIN-</sub> dominate, along with the selfnoise of R<sub>s</sub>



High-gain noise depends more on IC characteristics and source impedance than anything else

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### 1570/1583 Noise At Low Gains (0dB shown)

- e<sub>nIN+</sub> & e<sub>nIN-</sub> are small, along with the self-noise of R<sub>s</sub>
- R<sub>s</sub> is small, so the i<sub>IN+</sub> & i<sub>IN-</sub> contributions are small
- R<sub>G</sub> is open, so the two i<sub>nR<sub>G</sub></sub> currents flow through R<sub>A</sub> & R<sub>B</sub>
  - i<sub>nRG</sub> currents dominate the noise floor
- To reduce noise at low gains, reduce R<sub>A</sub> & R<sub>B</sub>



Low-gain noise depends more on IC characteristics and feedback  $(R_A \& R_B)$  impedance than anything else

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### 1510 (Front End) Noise At High Gains (60dB Shown)

- R<sub>G</sub> is small, so i<sub>nR<sub>G</sub></sub> contribution is small
- R<sub>s</sub> is small, so the i<sub>nIN+</sub> & i<sub>nIN-</sub> contributions are small
  - As with 1570, if R<sub>s</sub> is large (e.g., open inputs), i<sub>nIN</sub> contributions can be significant
- e<sub>nIN+</sub> & e<sub>nIN-</sub> dominate, along with the selfnoise of R<sub>s</sub>



High-gain noise depends more on IC characteristics and source impedance than anything else

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### 1510 (Front End) Noise At Low Gains (0dB Shown)

- e<sub>nIN+</sub> & e<sub>nIN-</sub> are small, along with the self-noise of R<sub>s</sub>
- R<sub>s</sub> is small, so the i<sub>nIN+</sub> & i<sub>nIN-</sub> contributions are small
- R<sub>G</sub> is open, so i<sub>nRG1</sub> flows through R<sub>A</sub>, & i<sub>nRG2</sub> flows through R<sub>B</sub>
  - i<sub>nRG</sub> currents dominate the noise floor
- Since R<sub>A</sub> & R<sub>B</sub> are fixed (internal), designers don't have freedom to affect this noise source



Noise at low gains depends only on IC characteristics: no flexibility with the "standard" topology

### **Controlling Noise:** "Standard" vs. "New" Topology

- High-gain noise is same (1nV/√Hz) across 1510, 1512, & 1570
- Low-gain noise can be controlled in new topology, but not in standard topology
  - Requires the designer to supply R<sub>A</sub> & R<sub>B</sub>



1570's OdB gain noise is~9dB lower compared to 1510,~5dB lower compared to 1512

### **Controlling Noise: "Standard" vs. "New" Topology**

- 1583 high-gain noise (1.9 nV/√Hz, or
   5.6dB) is higher than 1510, 1512, & 1570
- But, low-gain noise for the 1583 is almost as low as the 1512
- New topology preserves better lowgain noise, even with a higher-noise part



1583's 0dB gain noise is ~3dB lower than 1510 ~1.4dB higher than 1512

# **Optimization Details**

Noise

Bandwidth

Gain control, taper & DC offset Output & Common-Mode Rejection



# **Optimizing Bandwidth Vs. Gain**

- Bandwidth is determined by amplifier design and feedback resistor ( $R_A \& R_B$ )
- In 1510/12, you're limited to  $R_A = R_B = 5k\Omega$
- In 1570 & 1583, you can vary R<sub>A</sub> & R<sub>B</sub>
  - Lower values => higher bandwidth
  - Minimum value is  $\mathbf{Z}\mathbf{k}\Omega$

Gain (dB)	0	6	10	20	30	40	50	60	
Part									
1510	10.39	10.22	10.14	9.95	9.48	8.11	5.25	2.28	MHz
1512	11.95	11.84	11.65	11.15	9.76	6.66	3.04	1.07	MHz
1570 (2kΩ)	16.78	16.78	15.65	12.71	7.83	3.65	1.38	0.46	MHz
<b>1570 (5k</b> Ω)	4.19	4.19	4.19	3.91	3.41	2.41	1.12	0.43	MHz
1570 (10kΩ)	1.93	1.91	1.91	1.86	1.72	1.39	0.87	0.40	MHz
1583 (2kΩ)	13.97	13.00	12.01	8.73	4.33	1.69	0.59	0.19	MHz
1583 (5kΩ)	3.92	3.60	3.40	2.95	2.20	1.24	0.52	0.19	MHz
1583 (10kΩ)	1.56	1.50	1.47	1.38	1.19	0.84	0.44	0.17	MHz

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# **Optimization Details**

Noise Bandwidth Gain control, taper & DC offset Output & Common-Mode Rejection



### **Practical Considerations for R<sub>A</sub> & R<sub>B</sub>**

- R<sub>G</sub> is determined by maximum gain and R<sub>A</sub>, R<sub>B</sub> values
- To minimize output (differential) offset with gain, use C<sub>G</sub>
- C<sub>G</sub> works against R<sub>G</sub> to determine LF cutoff (f<sub>0</sub>)

   Small R<sub>G</sub> and low f<sub>0</sub> means big C<sub>G</sub>



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### Varying Gain in the "Standard" Circuit

- R<sub>G</sub> varies to set gain
- Max gain when R<sub>GV</sub> is maximum
- Min gain when R<sub>GV</sub> is minimum
- Highest lowfrequency cutoff occurs at max gain
- C<sub>G</sub> depends on desired LF cutoff and R<sub>GF</sub> value



 $C_{G}$ =3300 $\mu$ f,  $R_{G}$ =10 $\Omega$ ,  $f_{o}$ = 4.43Hz

### **Practical Considerations for Varying Gain in the "Standard Circuit"**

- Effective end resistance in R<sub>GV</sub> limits max gain

  - Reduce R<sub>GF</sub> to offset
     Variation in effective end resistance will alter max gain
- Pots used by APB **Dynasonics** have  $2 \sim 3\Omega$ (measured) end resistance
- Thanks to John Petrucelli for samples!
  - Check your spec sheet for your tolerances ...



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### **Practical Considerations for Varying Gain in the "New" Circuit**

- The conventional circuit is shown at right
- To minimize low-gain noise, select  $R_A \& R_B$  as low as possible – For 1570, that's  $2k\Omega$ 

  - For 1583, that's  $??\Omega$
- For 60dB gain,  $R_{GF} = 4\Omega$
- End resistance may be a significant fraction of R<sub>GE</sub>
- To maintain < 5Hz cutoff,</li> **C<sub>G</sub> > 7300**μ**f** 
  - That's a big, expensive cap
  - Is < 5Hz cutoff a good idea at</li> 60dB gain?



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### **Consider a Dual-Element Pot to vary** R<sub>G</sub>, R<sub>A</sub> & R<sub>B</sub> **Simultaneously**

- Using a dual-element pot allows R<sub>A</sub> & R<sub>B</sub> to vary in addition to R<sub>G</sub>
  - Lowers R<sub>A</sub> & R<sub>B</sub> at min gain, but raises them at max gain
- This allows smaller C<sub>G</sub> for the same cutoff
  - In circuit shown
    - f<sub>o</sub> ≈ 5.5Hz
  - 60dB gain noise is still very low: 1.18nV/√Hz (-129.1dBu with 150Ω source)



# **Pot Taper**

- Measured taper of "5% reverse log" taper pots (thanks to APB)
- Actually two linear sections with different resistances in each section
- What curve of gain vs. rotation will this produce?



### Gain vs. Rotation Compared: Single and Dual-Element Circuits

- Theoretical "ideal" curve shown in black
- Single-element pot (circuit of slide 26) results in red curve
- Dual-element pot (circuit of slide 29) results in blue curve
- Dual-element pot trajectory is much closer to "ideal"



# **Optimization Details**

Noise Bandwidth Gain control, taper & DC offset Output & Common-Mode Rejection



### **Single-Ended Output Stages**

- The 1570/1583 topology is differential in, differential out
  - Common-mode gain is always unity (0dB)
  - Differential gain varies with R<sub>G</sub>, R<sub>A</sub>, & R<sub>B</sub> (0~>60dB)
  - CMRR is equal to differential gain
  - Output has a (negative) common-mode DC offset of 1 diode drop (~-0.6V)
- To provide CMR at low gains, add a differential amplifier after the 1570/1583
- Choose carefully to avoid adding noise and limiting bandwidth
  - 1510/1512 includes a pretty quiet, wide-band amp
  - 1570/1583 allows designers flexibility in choosing this amplifier for even greater performance
  - Circuit at right (w/ 2114) compromises low-gain noise floor by only ~2.6 dB (for the 1570) and ~0.14 dB (for the 1583)





### **Differential Output Stages**

- In many cases (e.g., driving ADC), differential outputs are needed
- But, many designers want to remove common-mode signals
- Simple circuit (top, using 1286) has great common-mode rejection, fair noise performance
- More complex circuit (bottom, after Birt) maintains very low differential noise, but commonmode rejection depends on resistor matching





## **Differential Output Stages**

- Variation of Birt circuit suggested for driving A/D converters
  - Includes attenuation suitable for ~2VRMS differential drive
- 1570/1583 differential output allows designers to spend on highperformance circuits & opamps when necessary, or save money when cost is more important than performance



# **Summing Up**

### Why choose the "new" topology?



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## **Summary**

- "New" 1570 & 1583 topology is a subset of the "standard" one
- Removing feedback resistors gives designers freedom to change their values
  - Optimize noise
  - Optimize bandwidth
  - Minimize blocking capacitor value while maintaining optimum noise performance
  - Optimize gain vs. rotation for analog control
- Removing output amp offers more flexibility
  - Naturally provides a differential output
  - Allows designer to set common-mode rejection
  - Optimize noise performance
- Less really is more!

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